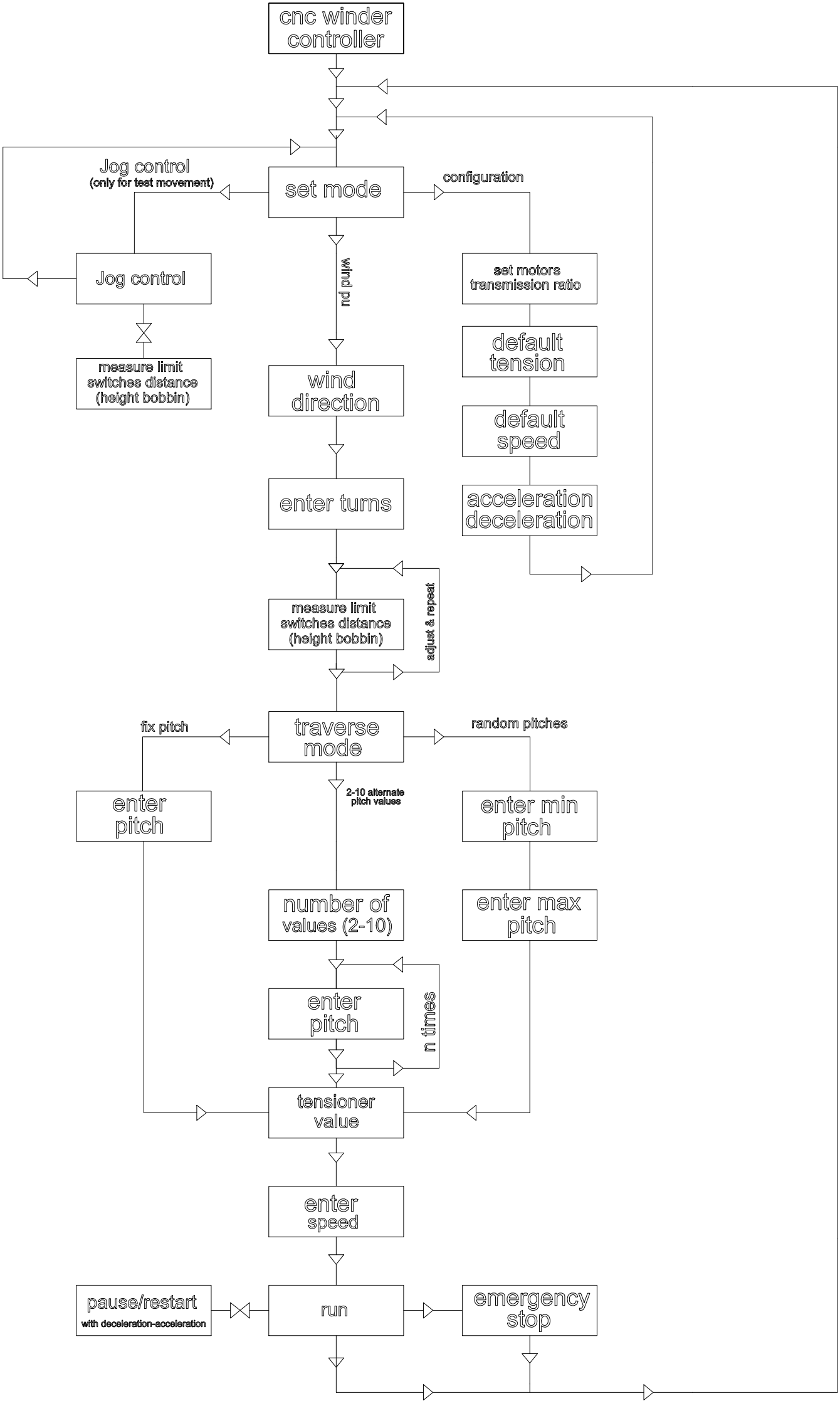
cnc winder controller
set mode
Jog control
(only for test movement)
configuration
Jog control
wind pu
set motors transmission ratio
measure limit switches distance (height bobbin)
wind direction
default tension
default speed
enter turns
acceleration deceleration
adjust & repeat
measure limit switches distance (height bobbin)
traverse mode
fix pitch
random pitches
enter pitch
2-10 alternate pitch values
enter min pitch
number of values (2-10)
enter max pitch
enter pitch
n times
tensioner value
enter speed
pause/restart
with deceleration-acceleration
run
emergency stop